

# Chapter 7

## Network Flow



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## \* 7.13 Assignment Problem

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# Assignment Problem

## Assignment problem.

- Input: **weighted**, complete bipartite graph  $G = (L \cup R, E)$  with  $|L| = |R|$ .
- Goal: find a perfect matching of **min weight**.

	1'	2'	3'	4'	5'
1	3	8	9	15	10
2	4	10	7	16	14
3	9	13	11	19	10
4	8	13	12	20	13
5	1	7	5	11	9

Min cost perfect matching

$M = \{ 1-2', 2-3', 3-5', 4-1', 5-4' \}$

$\text{cost}(M) = 8 + 7 + 10 + 8 + 11 = 44$

# Applications

## Natural applications.

- Match jobs to machines.
- Match personnel to tasks.
- Match PU students to writing seminars.

## Non-obvious applications.

- Vehicle routing.
- Signal processing.
- Virtual output queueing.
- Multiple object tracking.
- Approximate string matching.
- Enhance accuracy of solving linear systems of equations.

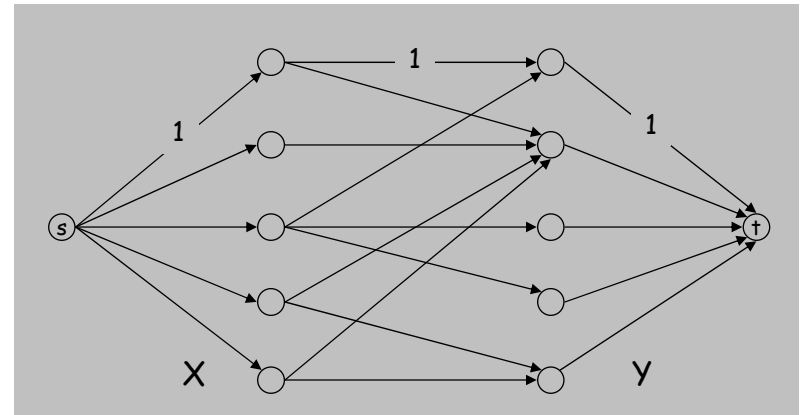
# Bipartite Matching

Bipartite matching. Can solve via reduction to max flow.

Flow. During Ford-Fulkerson, all capacities and flows are 0/1. Flow corresponds to edges in a matching  $M$ .

Residual graph  $G_M$  simplifies to:

- If  $(x, y) \notin M$ , then  $(x, y)$  is in  $G_M$ .
- If  $(x, y) \in M$ , the  $(y, x)$  is in  $G_M$ .
- If  $x$  is unmatched,  $(s, x)$  is in  $G_M$
- If  $y$  is unmatched,  $(y, t)$  is in  $G_M$

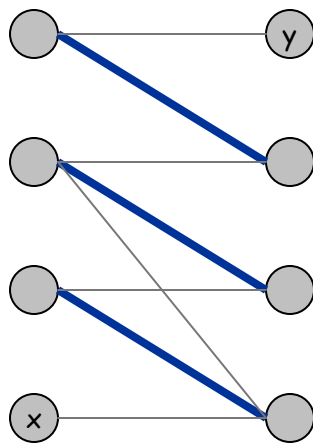


Augmenting path simplifies to:

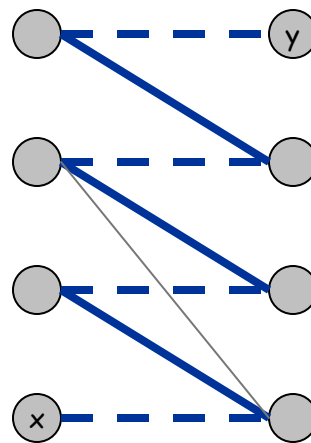
- Edge from  $s$  to an unmatched node  $x \in X$ .
- Alternating sequence of unmatched and matched edges.
- Edge from unmatched node  $y \in Y$  to  $t$ .

## Alternating Path

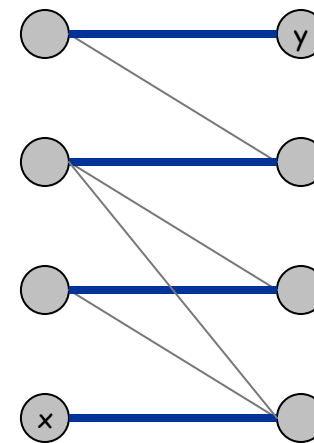
**Alternating path.** Alternating sequence of unmatched and matched edges, from unmatched node  $x \in X$  to unmatched node  $y \in Y$ .



matching  $M$



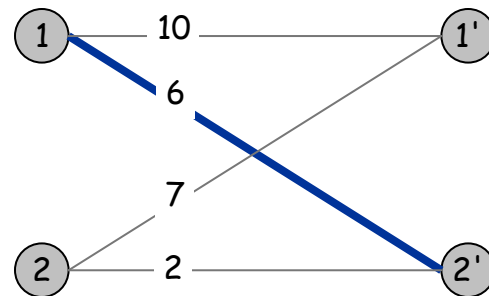
alternating path



matching  $M'$

## Assignment Problem: Successive Shortest Path Algorithm

Cost of an alternating path. Pay  $c(x, y)$  to match  $x-y$ ; receive  $c(x, y)$  to unmatch  $x-y$ .



$$\text{cost}(2 - 1') = 7$$

$$\text{cost}(2 - 2' - 1 - 1') = 2 - 6 + 10 = 6$$

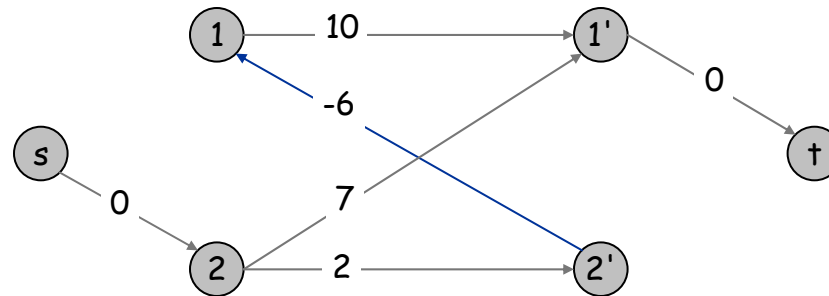
**Shortest alternating path.** Alternating path from any unmatched node  $x \in X$  to any unmatched node  $y \in Y$  with smallest cost.

**Successive shortest path algorithm.**

- Start with empty matching.
- Repeatedly augment along a **shortest** alternating path.

## Finding The Shortest Alternating Path

Shortest alternating path. Corresponds to shortest  $s$ - $t$  path in  $G_M$ .



**Concern.** Edge costs can be negative.

**Fact.** If always choose shortest alternating path, then  $G_M$  contains no negative cycles. The reason will be clear at the end  $\Rightarrow$  compute using Bellman-Ford.

**Our plan.** Use **duality** to avoid negative edge costs (and negative cost cycles)  $\Rightarrow$  compute using Dijkstra.



## Equivalent Assignment Problem

**Duality intuition.** Adding (or subtracting) a constant to every entry in row  $x$  or column  $y$  does not change the min cost perfect matching(s).

$c(x, y)$						$c^P(x, y)$				
3	8	9	15	10	subtract 11 from column 4 →	3	8	9	4	10
4	10	7	16	14		4	10	7	2	14
9	13	11	19	10		9	13	11	8	10
8	13	12	20	13		8	13	12	9	13
1	7	5	11	9		1	7	5	0	9
11										

## Equivalent Assignment Problem

**Duality intuition.** Adding  $p(x)$  to row  $x$  and subtracting  $p(y)$  from column  $y$  does not change the min cost perfect matching(s).

$c(x, y)$						$c^p(x, y)$					
3	8	9	15	10	5	0	0	3	1	2	
4	10	7	16	14	4	0	1	0	1	5	
9	13	11	19	10	3	4	3	3	3	0	
8	13	12	20	13	0	0	0	1	1	0	
1	7	5	11	9	8	1	2	2	0	4	
8	13	11	19	13							↑ $9 + 8 - 13$

## Reduced Costs

Reduced costs. For  $x \in X, y \in Y$ , define  $c^p(x, y) = p(x) + c(x, y) - p(y)$ .

Observation 1. Finding a min cost perfect matching with reduced costs is equivalent to finding a min cost perfect matching with original costs.

$c(x, y)$					→	$c^p(x, y)$					
3	8	9	15	10	5	0	0	3	1	2	
4	10	7	16	14	4	0	1	0	1	5	
9	13	11	19	10	3	4	3	3	3	0	
8	13	12	20	13	0	0	0	1	1	0	
1	7	5	11	9	8	1	2	2	0	4	↑
8	13	11	19	13							9 + 8 - 13

## Compatible Prices

**Compatible prices.** For each node  $v$ , maintain prices  $p(v)$  such that:

- (i)  $c^p(x, y) \geq 0$  for for all  $(x, y) \notin M$ .
- (ii)  $c^p(x, y) = 0$  for for all  $(x, y) \in M$ .

**Observation 2.** If  $p$  are compatible prices for a **perfect** matching  $M$ , then  $M$  is a min cost perfect matching.

$c(x, y)$						$c^p(x, y)$				
3	8	9	15	10	5	0	0	3	1	2
4	10	7	16	14	4	0	1	0	1	5
9	13	11	19	10	3	4	3	3	3	0
8	13	12	20	13	0	0	0	1	1	0
1	7	5	11	9	8	1	2	2	0	4
8	13	11	19	13	→					

$$\text{cost}(M) = \sum_{(x, y) \in M} c(x, y) = (8+7+10+8+11) = 44$$

$$\text{cost}(M) = \sum_{y \in Y} p(y) - \sum_{x \in X} p(x) = (8+13+11+19+13) - (5+4+3+0+8) = 44$$

# Successive Shortest Path Algorithm

Successive shortest path.

```
Successive-Shortest-Path(X, Y, c) {  
  M ←  $\phi$   
  foreach x ∈ X: p(x) ← 0  
  foreach y ∈ Y: p(y) ← mine into y c(e)           p is compatible  
                                                    with M =  $\phi$   
  
  while (M is not a perfect matching) {  
    Compute shortest path distances d  
    P ← shortest alternating path using costs cP  
    M ← updated matching after augmenting along P  
    foreach v ∈ X ∪ Y: p(v) ← p(v) + d(v)  
  }  
  return M  
}
```

## Maintaining Compatible Prices

**Lemma 1.** Let  $M'$  be matching obtained by augmenting along a min cost path with respect to  $c^{p+d}$ . Then  $p' = p + d$  is compatible with  $M'$ .

**Pf.**

- **Case 1.**  $(x,y)$  in  $M$ . By construction, the only edge that arrives at  $x$  is  $G_M$  is  $(y,x)$ . This implies that  $d(x)=d(y) - ( c(x,y)+p(x) -p(y) )$ . Thus,  
$$c^{p+d}(x, y) = c(x,y) + p(x) -p(y) + d(x)- d(y)=0.$$
- **Case 2**  $(x,y)$  in  $M' - M$ .  $(x,y)$  belongs to the shortest path in  $G_M$ . We must have  $d(y)=d(x) + ( c(x,y)+p(x) -p(y) )$ . Thus,  
$$c^{p+d}(x, y) = c(x,y) + p(x) -p(y) + d(x)- d(y)=0.$$
- **Case 3.**  $(x,y)$  is not in  $M \cup M'$ . In this case,  $(x,y)$  in  $G_M$ . We have that  $d(y) \leq d(x) + ( c(x,y)+p(x) -p(y) )$ . Thus,  
$$c^{p+d}(x, y) = c(x,y) + p(x) -p(y) + d(x)- d(y) \geq 0.$$

## Successive Shortest Path: Analysis

**Invariant.** The algorithm maintains a matching  $M$  and compatible prices  $p$ .

**Pf.** Follows from Lemmas 1 and initial choice of prices. ■

**Theorem.** The algorithm returns a min cost perfect matching.

**Pf.** Upon termination  $M$  is a perfect matching, and  $p$  are compatible prices. Optimality follows from Observation 2. ■

**Theorem.** The algorithm can be implemented in  $O(n^3)$  time.

**Pf.**

- Each iteration increases the cardinality of  $M$  by 1  $\Rightarrow$   $n$  iterations.
- Bottleneck operation is computing shortest path distances  $d$ .  
Since all costs are nonnegative, each iteration takes  $O(n^2)$  time using (dense) Dijkstra. ■

## Weighted Bipartite Matching

**Weighted bipartite matching.** Given weighted bipartite graph, find maximum cardinality matching of minimum weight. ↖ m edges, n nodes

**Successive shortest path algorithm.**  $O(mn \log n)$  time using heap-based version of Dijkstra's algorithm.

**Best known bounds.**  $O(mn^{1/2})$  deterministic;  $O(n^{2.376})$  randomized.

**Planar weighted bipartite matching.**  $O(n^{3/2} \log^5 n)$ .